What You Can See in Limited Data Tomography

Todd Quinto

Tufts University

http://equinto.math.tufts.edu

Joint work with Jürgen Frikel Technical University of Denmark and Fachhochschule Regensburg

> Bernadette Hahn Universität Würzburg

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 Motion-Compensated CT: CT when the body moves during the scan.

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Limited Data Tomography: When some data are missing.

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Limited Data Tomography: When some data are missing.

Example:

• Limited angle X-ray CT [A. Louis, X. Pan, G. Wang. . .] the scanner cannot move all the way around the object–it images the object from lines in a limited range of directions. Where: Dental CT, ~electron microscope tomography.

Limited angle data over "somewhat" vertical lines.



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~Horizontal lines are missing.

Goals of this talk:

Determine what features of the body will be easy to reconstruct from limited CT data, and which will be difficult.



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Determine what features of the body will be easy to reconstruct from limited CT data, and which will be difficult.

2 Understand, geometrically, how this depends on the data.



f a function in the plane representing the density of an object *L* a line in the plane over which the photons travel. The X-ray (Radon) Line Transform:

Tomographic Data
$$\sim Rf(L) = \int_{x \in L} f(x) ds$$

-The 'amount' of material on the line the X-rays traverse.



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The goal: Recover a picture of the body (values of f(x)), from X-ray CT data over a finite number of lines.

With *complete data* (lines throughout the object in fairly evenly spaced directions), good reconstruction methods exist (e.g., Filtered Backprojection [Natterer, Natterer-Wübbling]).

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GE scanner



GE Reconstruction





Parallel Beam Geometry (~fan beam but simpler):

The angle: $\varphi \in [0, 2\pi], \quad \theta(\varphi) = (\cos(\varphi), \sin(\varphi))$

The line over which X-rays travel: $L(\varphi, p)$ is the line perpendicular to φ and p units from the origin (in opposite direction if p < 0)





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The object: *f* is the density function of an object in the plane. **Tomographic data:** $Rf(\varphi, p) = \int_{x \in L(\varphi, p)} f(x) ds$ is given when X-rays travel along the line $L(\varphi, p)$.

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Limited Angle Tomography, $\varphi^{-1}[-\pi/4,\pi/4]$





Brain phantom (left) [radiopedia.org], FBP reconstruction [Frikel, Q 2013]



Limited Angle Tomography, $\varphi^{-1}[-\pi/4, \pi/4]$







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• Which features of the object are visible in the reconstruction? Which are invisible?

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Brain phantom (left) [radiopedia.org], FBP reconstruction [Frikel, Q 2013]

- Which features of the object are visible in the reconstruction? Which are invisible?
- Are there added artifacts?

The features of the object are (partly) characterized by the singularities of the object.



Big Question

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- What are singularities?



The function



Big Question

- The features of the object are (partly) characterized by the singularities of the object.
- What are singularities?
 - *Practically:* Density jumps, boundaries between regions, discontinuities of *f*.
 - *Mathematically:* Where the function is not C^{∞} smooth.



The function



Its singularities (sing. supp.)



Find line integrals Rf over vertical lines if f is the characteristic function of the unit disk. \rightarrow













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In terms of wavefront sets: If some wavefront direction of *f* is *perpendicular* to $L(\varphi_0, p_0)$, then *Rf* has WF above (φ_0, p_0) .

The Moral:

• The Microlocal Regularity Theorem \implies If *f* has a singularity tangent to the line L_0 , then *Rf* will have a singularity at L_0 .



The Moral:

● The Microlocal Regularity Theorem → If *f* has a singularity tangent to the line L₀, then *Rf* will have a singularity at L₀. In this case, the singularity should be "easy" to reconstruct stably from limited data as long as L₀ is in the data set.

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- If a singularity of f is not tangent to any line in the data set, then, it will be harder to see in the data



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Moral for limited data CT: If the line L_0 is in a limited data set, then singularities of f tangent to L_0 should be "easy" to reconstruct from that data. Singularities of f not tangent to any line in the data set will be harder to reconstruct (less stable).

Limited Angle Reconstruction Revisited



Reconstruction for lines with $\varphi \in [-\pi/4, \pi/4]$ [Frikel, Q 2013]. \longrightarrow



Limited Angle Reconstruction Revisited



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 As predicted, the visible singularities are tangent to lines in the data set. They are the "~vertical" boundaries.

 Singularities not tangent to lines in the data set-the "~horizontal" boundaries-are blurred.

Limited Angle Reconstruction Revisited



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- As predicted, the visible singularities are tangent to lines in the data set. They are the "~vertical" boundaries.
- Singularities not tangent to lines in the data set-the "~horizontal" boundaries-are blurred.
- But, what about the streaks....?



The Added Artifacts for data with $\phi \in [-\pi/4, \pi/4]$





The Added Artifacts for data with $\phi \in [-\pi/4, \pi/4]$



Note how the singularities of *f* tangent to lines at the ends of the angular range, $L(\pm \pi/4, p)$, generate added artifacts all along the lines tangent to them.

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Added Artifacts for data with $\varphi \in [-\pi/4, \pi/4]$



If data are given for φ between a and b, then artifacts will occur on lines with $\varphi = a$ and $\varphi = b$ when those lines are tangent to a singularity (boundary) of the object.



Added Artifacts



Theorem ([Frikel Q 2013])

For limited angle tomography, added artifacts will occur on lines at the end of the angular range

-from X-rays at the start and end of the scanthat are tangent to some singularity in the object.



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Our (simple practical) Artifact Reduction Procedure

Assume the limited angle data are given for $\varphi \in [a, b]$.

modified data = $[\kappa(\varphi)Rf](\varphi, p)$

where κ is a smooth cutoff function equal to zero off of [a, b] and equal to one on most of [a, b].





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then there will be no added streak artifacts and most visible singularities will be recovered [Frikel Q 2013,2015].

Hybrid imaging: Thermoacoustic Tomography (TAT)

- Pulsed electromagnetic (EM) radiation (radio waves (PAT: laser light)) is beamed into a part of the body (e.g., breast).
- The body heats up and generates sound pressure waves that are measured by acoustic transducers.



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- The body heats up and generates sound pressure waves that are measured by acoustic transducers.
- Sometimes TAT/PAT transducers are collimated to a plane and they move along the unit circle [Razansky 2009, Elbau 2012].
- These transducers measure the sound pressure over time and, by solving the wave equation (with constant sound speed), this can be reduced to the integrals over circles of the initial value of the acoustic pressure, *f*.







Limited Data Acquisition Curve

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Limited Data PAT: When transducers cannot scan all around the object (e.g., because of specimen holder), so data are given only for centers $\theta(\varphi)$ for $a \leq \varphi \leq b$.

Limited data PAT reconstructions



Simulated data, $\varphi \in [25^\circ, 155^\circ]$

Real data, $\varphi \in [-45^\circ, 225^\circ]$



Limited data PAT reconstructions



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• Why is the circle not completely imaged?

Limited data PAT reconstructions



Simulated data, $\varphi \in [25^{\circ}, 155^{\circ}]$ Real data, $\varphi \in [-45^{\circ}, 225^{\circ}]$

- Why is the circle not completely imaged?
- Why are there streak artifacts in both reconstructions?



PAT data are \sim averages over circles.

Theorem (Frikel Q 2015)

Visible singularities of f are tangent to circles in the data set



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PAT data are \sim averages over circles.

Theorem (Frikel Q 2015)

Visible singularities of f are tangent to circles in the data set Invisible singularities are tangent to NO circle in the data set.



Added artifacts occur when a circle at the ends of the data set (center $\theta(a)$ or $\theta(b)$) is tangent to a singularity of *f*.



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Added artifacts occur when a circle at the ends of the data set (center $\theta(a)$ or $\theta(b)$) is tangent to a singularity of f. The singularity spreads along the entire circle!



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Limited view reconstructions revisited



Lambda reconstruction for range of view [25°, 155°]. Note the added artifacts are along circles centered at $\theta(25^\circ)$ and $\theta(155^\circ)$.

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Real data reconstructions, φ between -45° to 225°



No artifact reduction With artifact reduction Difference Image

Paper phantom with ink as acoustic absorber¹. ¹ Data by courtesy of Prof. Daniel Razansky (Institute of Biological and Medical Imaging, Helmholtz Zentrum München).



Real data reconstructions, φ between -45° to 225°



No artifact reduction With artifact reduction Difference Image

Paper phantom with ink as acoustic absorber¹. ¹ Data by courtesy of Prof. Daniel Razansky (Institute of Biological and Medical Imaging, Helmholtz Zentrum München).

The added artifacts are exactly as predicted–they occur on circles at the ends of the data set



The Paradigm: *f* is the function to be reconstructed. If the tomography problem is modeled by a transform that averages over curves (e.g., X-ray CT, TAT/PAT, Motion compensated CT), then:

- If a curve in the data set is tangent to a singularity of *f* then it should be stably reconstructed.
- If no curve in the data set is tangent to a singularity, it will be difficult to reconstruct.



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- Artifacts can be spread along curves at the end of the data set when those curves are tangent to some singularity of f.



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Our reconstructions are of filtered backprojection type. *Other reconstruction methods might reconstruct the invisible singularities better, but invisible singularities will always be difficult to reconstruct (highly ill-posed).*



The Proof

[Q 1993, Frikel Q 2013, Frikel Q 2015, Hahn Q 2016] use the following keys.

Singularity: Fourier transform and the wavefront set.



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- Singularity: Fourier transform and the wavefront set.
- Fourier Integral Operator (FIO): the X-ray and TAT/PAT transforms are elliptic FIO (Radon transforms are elliptic FIO [Guillemin] FIO) and they do precise things to singularities.



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- This math works for man tomographic inverse problems including higher dimensional ones (e.g., sonar, 3-D ultrasound) under certain conditions.
- When these conditions don't hold, one can still use the basic framework (discussions at DTU: Borg, Frikel, Jørgenson, Lauze, Q).


The Proof and The Final Word

[Q 1993, Frikel Q 2013, Frikel Q 2015, Hahn Q 2016] use the following keys.

- Singularity: Fourier transform and the wavefront set.
- Fourier Integral Operator (FIO): the X-ray and TAT/PAT transforms are elliptic FIO (Radon transforms are elliptic FIO [Guillemin] FIO) and they do precise things to singularities.
- This math works for man tomographic inverse problems including higher dimensional ones (e.g., sonar, 3-D ultrasound) under certain conditions.
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Final word: Invisible singularities and added artifacts are intrinsic to limited data tomography and they can be understood using the geometry of the data set.





The reconstruction operator for Limited angle CT

$$m{B}_{\Phi}m{f}=m{R}^{*}\left(\sqrt{-m{d}^{2}/m{d}p^{2}}\chi_{[m{a},b]}m{R}m{f}
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where R^* is the X-ray backprojection operator.

 In [FrQu2013], we prove that B_Φ is a singular pseudodifferential operator, and we use a theorem of Hörmander to characterize the added artifacts.

$$V_{\Phi} = \left\{ s\theta(\varphi) \middle| s \neq 0, \ \varphi \in (-\Phi, \Phi) \right\}$$
$$B_{\Phi}f(x) = \frac{1}{2\pi} \int_{\xi \in V_{\Phi}} e^{ix \cdot \xi} \mathbf{1} \ \mathcal{F}f(\xi) d\xi$$



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 The symbol of B_Φ as a pseudodifferential operator is p(x, ξ) = 1_{V_Φ}(ξ), which is elliptic on V_Φ, so B_Φ recovers singularities of *f* in V_Φ. But it is not smooth, so the operator is singular

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• The symbol of B_{Φ} as a pseudodifferential operator is $p(x,\xi) = \mathbf{1}_{V_{\Phi}}(\xi)$, which is elliptic on \mathcal{V}_{Φ} , so B_{Φ} recovers singularities of f in \mathcal{V}_{Φ} . But it is not smooth, so the operator is singular Therefore, B_{Φ} adds the singularities described in the theorem.

If κ is the smooth function supported in $(-\Phi, \Phi)$ and equal to one on $(-\Phi + \varepsilon, \Phi - \varepsilon)$, then we prove that

$$B_{\Phi,\kappa}f = \frac{1}{2\pi} \int_{\xi \in V_{\Phi}} e^{i x \cdot \xi} \kappa\left(\frac{\xi}{\|\xi\|}\right) \mathcal{F}f(\xi) d\xi$$

Note that the symbol of B_Φ as a pseudodifferential operator is p(x, ξ) = κ (ξ/||ξ||), which is elliptic, at least on V_(-Φ+ε,Φ-ε).



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- Note that the symbol of B_Φ as a pseudodifferential operator is p(x, ξ) = κ (ξ/||ξ||), which is elliptic, at least on V_(-Φ+ε,Φ-ε). Therefore, B_Φ recovers most of the visible singularities of *f*.
- Furthermore, since the symbol is smooth, B_{Φ,κ} is a standard pseudodifferential operator and does not adds singularities.

シック・ビデュ・ボッ・ボッ・セッ・

Z and *X* are open subsets of \mathbb{R}^n :

$$F(f)(z) = \int_{x \in X, \omega \in \mathbb{R}^n} e^{i\phi(z, x, \omega)} p(z, x, \omega) f(x) dx d\omega$$



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 $\mathcal{C} = \{(z, \partial_z \phi(z, x, \omega); x, -\partial_x \phi(z, x, \omega)) | \partial_\omega \phi(z, x, \omega) = \mathbf{0}\}$





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WF relation: WF(F(f)) $\subset \Pi_L \left(\Pi_R^{-1}(WF(f)) \right)$. What it means: FIO change singularities in specific ways determined by the geometry of \mathcal{C} . う 2 (1) (



Pseudodifferential operators

$$P(f)(z) = \int e^{i(z-x)\cdot\omega} p(z,x,\omega) f(x) dx d\omega$$

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$$P(f)(z) = \int e^{i(z-x)\cdot\omega} p(z,x,\omega) f(x) dx \, d\omega$$

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The filter: $\Lambda_p g(\varphi, p) = \frac{1}{\sqrt{2\pi}} \int_{p=-\infty}^{\infty} e^{-i\tau(p-s)} |\tau| g(\varphi, s) \, ds \, d\tau$ (like a derivative).



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Filtered Back Projection Operator:

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Limited Angle Filtered Back Projection Operator:

$$f(x) = \frac{1}{4\pi} R^* \left(\Lambda_{\rho} R f \right)(x) \quad B_{\Phi} f(x) := \frac{1}{4\pi} R^* \left(\Lambda_{\rho} \mathbf{1}_{\left[-\Phi,\Phi\right]} R f \right)(x)$$

Where $\mathbf{1}_{[-\Phi,\Phi]}(\phi)$ is 1 on the interval $[-\Phi,\Phi]$ and 0 elsewhere. It sets data outside the known region to zero.

Visible Singularities: \mathcal{V}_{Φ} , those perpendicular to lines in the data set (corresponding to "side" boundaries of the object).



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Theorem (Frikel, Q 2013)

Let $f \in \mathcal{E}'(\mathbb{R}^2)$. Then

 B_Φf shows the visible singularities of f (those perpendicular to lines in the data set), WF(f) ∩ V_Φ ⊂ WF (B_Φ(f))

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