



Time Series Analysis

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Outline of the lecture

Regression based methods, 1st part:

- Introduction (Sec. 3.1)
- The General Linear Model, including OLS-, WLS-, and ML-estimates (Sec. 3.2)
- Prediction in the General Linear Model (Sec. 3.3)
- Examples...



General form of the regression model

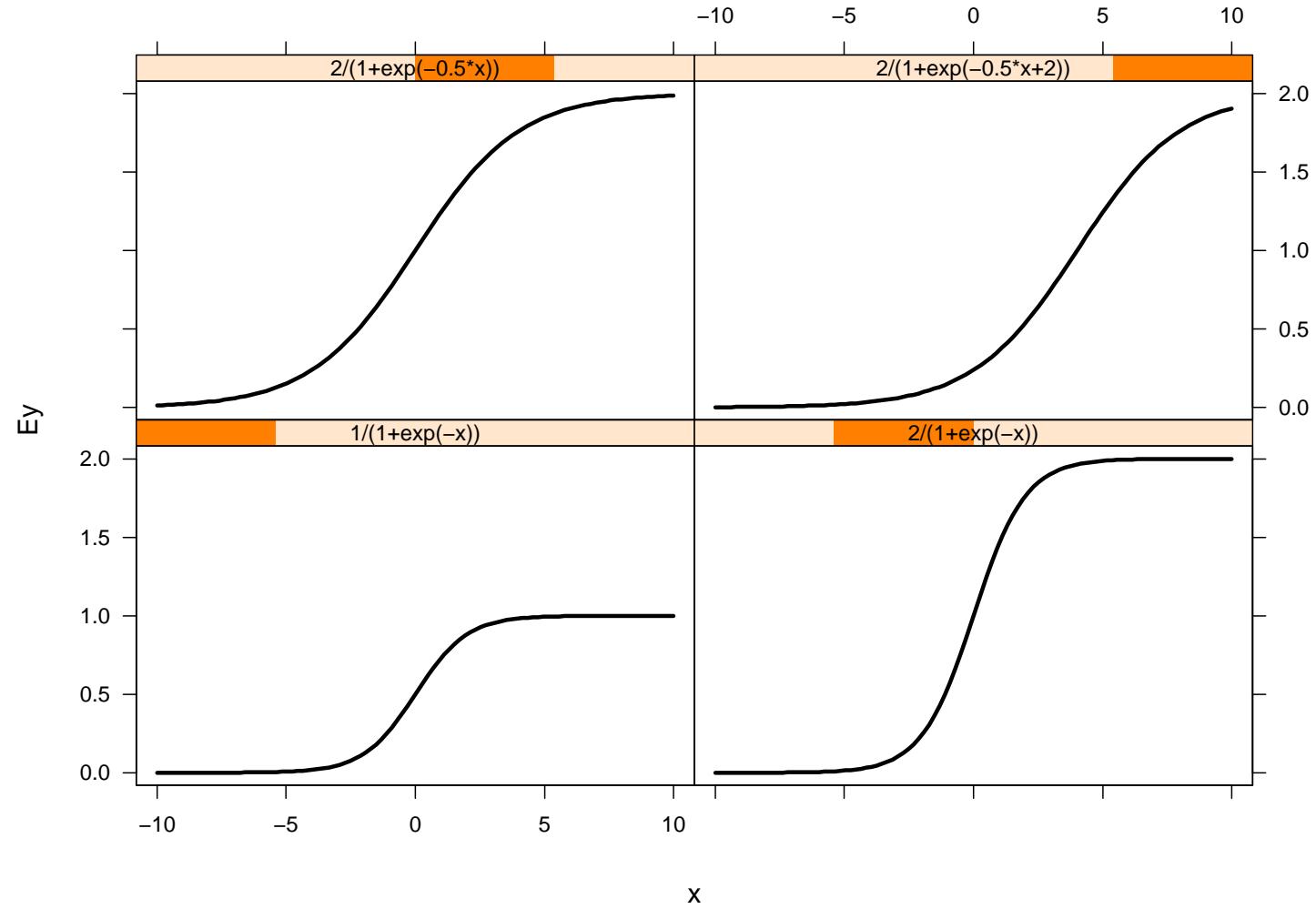
$$Y_t = f(\mathbf{X}_t, t; \boldsymbol{\theta}) + \varepsilon_t$$

Where:

- Y_t is the output we aim to model
- \mathbf{X}_t indicates the p independent variables $\mathbf{X}_t = (X_{1t}, \dots, X_{pt})^T$
- t is the time index
- $\boldsymbol{\theta}$ indicates m unknown parameters $(\theta_1, \dots, \theta_m)^T$
- ε_t is a sequence of random variables with mean zero, variance σ_t , and $Cov[\varepsilon_{t_i}, \varepsilon_{t_j}] = \sigma \Sigma_{ij}$

We restrict the discussion to the case where \mathbf{X}_t is non-random and we write x_t

$$Y_t = \theta_1 / (1 + \exp(-\theta_2 x_t + \theta_3)) + \varepsilon_t$$





Least squares estimates

Observations:

$$(y_1, \mathbf{x}_1), (y_2, \mathbf{x}_2), \dots, (y_n, \mathbf{x}_n)$$

Ordinary Least Square (unweighted) estimates is found from

$$\hat{\boldsymbol{\theta}} = \arg \min_{\boldsymbol{\theta}} S(\boldsymbol{\theta})$$

where

$$S(\boldsymbol{\theta}) = \sum_{t=1}^n [y_t - f(\mathbf{x}_t; \boldsymbol{\theta})]^2 = \sum_{t=1}^n \varepsilon_t^2(\boldsymbol{\theta})$$

The unweighted method assumes that the errors all have the same variance and are mutually uncorrelated.

Variance of error and estimates

If the model errors ε_t are i.i.d.

- The variance of the model errors is estimated as:

$$\hat{\sigma}^2 = \frac{S(\hat{\theta})}{n - p}$$

- The variance-covariance matrix of the estimates is

$$V[\hat{\theta}] = 2\hat{\sigma}^2 \left[\frac{\partial^2}{\partial^2 \theta} S(\theta) \right]^{-1} \Big|_{\theta=\hat{\theta}}$$



The General Linear Model

$$Y_t = x_t^T \boldsymbol{\theta} + \varepsilon_t$$



The General Linear Model

$$Y_t = \mathbf{x}_t^T \boldsymbol{\theta} + \varepsilon_t$$

Note that the quadratic model

$$Y_t = \theta_0 + \theta_1 z_t + \theta_2 z_t^2 + \varepsilon_t$$

can be written

$$y_t = \begin{pmatrix} 1 & z_t & z_t^2 \end{pmatrix} \begin{pmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{pmatrix} + \varepsilon_t$$

and hence it is a general linear model.



General Linear Models

- Some examples in the book
- (Multiple) regression analysis, ex: $Y = \alpha + \beta x + \varepsilon$
- Analysis of variance, ex: $Y = \alpha_i + \varepsilon$ (i indexes the treatment)
- Analysis of covariance, ex: $Y = \alpha_i + \beta x + \varepsilon$

For ANOVA and ANCOVA the treatments must be coded into a number of x -variables.



OLS – solution

- Non-linear regression: Numerical optimization is required; see the book for a simple example (Newton-Raphson)
- For the general linear model a closed-form solution exists. For all observations the model equations are written as:

$$\begin{bmatrix} Y_1 \\ \vdots \\ Y_n \end{bmatrix} = \begin{bmatrix} \mathbf{x}_1^T \\ \vdots \\ \mathbf{x}_n^T \end{bmatrix} \boldsymbol{\theta} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix} \quad \text{or} \quad \mathbf{Y} = \mathbf{x}\boldsymbol{\theta} + \boldsymbol{\varepsilon}$$

i.e. we want to minimize $\boldsymbol{\varepsilon}^T \boldsymbol{\varepsilon}$

- The solution is $\hat{\boldsymbol{\theta}} = (\mathbf{x}^T \mathbf{x})^{-1} \mathbf{x}^T \mathbf{Y}$ (if \mathbf{x} has full rank)
- $\hat{\sigma}^2 = \boldsymbol{\varepsilon}^T \boldsymbol{\varepsilon} / (n - p)$ and $V[\hat{\boldsymbol{\theta}}] = \hat{\sigma}^2 (\mathbf{x}^T \mathbf{x})^{-1}$

Example

Data:

t	y	x
1	0.2	0.4
2	1.2	1.2
3	1.9	2.3
4	2.3	3.4
5	1.9	4.3

Model:

$$Y_t = \theta_0 + \theta_1 x_t + \theta_2 x_t^2 + \varepsilon_t$$

Example

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Model:

$$Y_t = \theta_0 + \theta_1 x_t + \theta_2 x_t^2 + \varepsilon_t$$

$$\mathbf{Y} = \mathbf{x}\boldsymbol{\theta} + \boldsymbol{\varepsilon}$$

Example

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Model:

$$Y_t = \theta_0 + \theta_1 x_t + \theta_2 x_t^2 + \varepsilon_t$$

$$\mathbf{Y} = \mathbf{x}\boldsymbol{\theta} + \boldsymbol{\varepsilon}$$

$$\begin{bmatrix} 0.2 \\ 1.2 \\ 1.9 \\ 2.3 \\ 1.9 \end{bmatrix} = \begin{bmatrix} 1 & 0.4 & 0.16 \\ 1 & 1.2 & 1.44 \\ 1 & 2.3 & 5.29 \\ 1 & 3.4 & 11.56 \\ 1 & 4.3 & 18.49 \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \\ \varepsilon_4 \\ \varepsilon_5 \end{bmatrix}$$

Example

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Model:

$$Y_t = \theta_0 + \theta_1 x_t + \theta_2 x_t^2 + \varepsilon_t$$

$$\mathbf{Y} = \mathbf{x}\boldsymbol{\theta} + \boldsymbol{\varepsilon}$$

$$\begin{bmatrix} 0.2 \\ 1.2 \\ 1.9 \\ 2.3 \\ 1.9 \end{bmatrix} = \begin{bmatrix} 1 & 0.4 & 0.16 \\ 1 & 1.2 & 1.44 \\ 1 & 2.3 & 5.29 \\ 1 & 3.4 & 11.56 \\ 1 & 4.3 & 18.49 \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \\ \varepsilon_4 \\ \varepsilon_5 \end{bmatrix}$$

$$\hat{\boldsymbol{\theta}} = (\mathbf{x}^T \mathbf{x})^{-1} \mathbf{x}^T \mathbf{Y} = \begin{bmatrix} -0.40 \\ 1.61 \\ -0.25 \end{bmatrix}$$



Properties

- It is a linear function of the observations Y (and \hat{Y} is a linear function of the observations)
- It is unbiased, i.e. $E[\hat{\theta}] = \theta$
- $V[\hat{\theta}] = E[(\hat{\theta} - \theta)(\hat{\theta} - \theta)^T] = \sigma^2(\mathbf{x}^T \mathbf{x})^{-1}$
- $\hat{\theta}$ is BLUE (Best Linear Unbiased Estimator), which means that it has the smallest variance among all estimators which are a linear function of the observations.



WLS-estimates

- Equations for all observations: $\mathbf{Y} = \mathbf{x}\boldsymbol{\theta} + \boldsymbol{\varepsilon}$
- $E[\boldsymbol{\varepsilon}] = \mathbf{0}$ and $V[\boldsymbol{\varepsilon}] = E[\boldsymbol{\varepsilon}\boldsymbol{\varepsilon}^T] = \sigma^2\boldsymbol{\Sigma}$, where $\boldsymbol{\Sigma}$ is known
- We want to minimize $(\mathbf{Y} - \mathbf{x}\boldsymbol{\theta})^T\boldsymbol{\Sigma}^{-1}(\mathbf{Y} - \mathbf{x}\boldsymbol{\theta})$ (why?)
- The solution is

$$\hat{\boldsymbol{\theta}} = (\mathbf{x}^T\boldsymbol{\Sigma}^{-1}\mathbf{x})^{-1}\mathbf{x}^T\boldsymbol{\Sigma}^{-1}\mathbf{Y}$$

(if $\mathbf{x}^T\boldsymbol{\Sigma}^{-1}\mathbf{x}$ is invertible)

- An unbiased estimate of σ^2 is

$$\hat{\sigma}^2 = \frac{1}{n-p}(\mathbf{Y} - \mathbf{x}\hat{\boldsymbol{\theta}})^T\boldsymbol{\Sigma}^{-1}(\mathbf{Y} - \mathbf{x}\hat{\boldsymbol{\theta}})$$



Example WLS/OLS

- H. Madsen & P. Thyregod (1988). *Modelling the Time Correlation in Hourly Observations of Direct Radiation in Clear Skies*. Energy and Buildings, 11, 201–211.
- See the examples in the book.



ML-estimates

- We now assume that the observations are Gaussian:

$$\mathbf{Y} \sim \mathcal{N}_n(\mathbf{x}\boldsymbol{\theta}, \sigma^2 \boldsymbol{\Sigma})$$

- $\boldsymbol{\Sigma}$ is assumed known
- The ML-estimator is the same as the WLS-estimator:

$$\hat{\boldsymbol{\theta}} = (\mathbf{x}^T \boldsymbol{\Sigma}^{-1} \mathbf{x})^{-1} \mathbf{x}^T \boldsymbol{\Sigma}^{-1} \mathbf{Y}$$

- The ML-estimator for σ^2 is

$$\hat{\sigma}^2 = \frac{1}{n} (\mathbf{Y} - \mathbf{x}\hat{\boldsymbol{\theta}})^T \boldsymbol{\Sigma}^{-1} (\mathbf{Y} - \mathbf{x}\hat{\boldsymbol{\theta}})$$



Properties of the ML-estimator

- It is a linear function of the observations which now implies that it is normally distributed
- It is unbiased, i.e. $E[\hat{\theta}] = \theta$ and
- The variance $V[\hat{\theta}] = E[(\hat{\theta} - \theta)(\hat{\theta} - \theta)^T] = (\mathbf{x}^T \Sigma^{-1} \mathbf{x})^{-1} \sigma^2$
- It is an efficient estimator



Unknown Σ

Relaxation algorithm:

- a) Select a value for Σ (e.g. $\Sigma = I$).
- b) Find the estimates for this value of Σ e.g. by solving the normal equations.
- c) Consider the residuals $\{\hat{\epsilon}_t\}$ and calculate the correlation and variance structure of the residuals. Then select a new value for Σ which reflects that correlation and variance structure.
- d) Stop if convergence - otherwise go to b).

See (Goodwin and Payne, 1977) for details.



Prediction

- If the expected value of the squared prediction error is to be minimized, then
- we must use the expected mean $E[Y|X = x]$ as the prediction.



Prediction in the general linear model

- Known parameters:

$$\hat{Y}_{t+\ell} = E[Y_{t+\ell} | \mathbf{X}_{t+\ell} = \mathbf{x}_{t+\ell}] = \mathbf{x}_{t+\ell}^T \boldsymbol{\theta}$$

$$V[Y_{t+\ell} - \hat{Y}_{t+\ell}] = V[\varepsilon_{t+\ell}] = \sigma^2$$

- Estimated parameters:

$$\hat{Y}_{t+\ell} = E[Y_{t+\ell} | \mathbf{X}_{t+\ell} = \mathbf{x}_{t+\ell}] = \mathbf{x}_{t+\ell}^T \hat{\boldsymbol{\theta}}$$

$$V[Y_{t+\ell} - \hat{Y}_{t+\ell}] = V[\varepsilon_{t+\ell}] = \sigma^2 [1 + \mathbf{x}_{t+\ell}^T (\mathbf{x}^T \mathbf{x})^{-1} \mathbf{x}_{t+\ell}]$$



Prediction in the general linear model – continued

- We must use an estimate of σ and therefore a $100(1 - \alpha)\%$ prediction interval of a future value is calculated as:

$$\hat{Y}_{t+\ell} \pm t_{\alpha/2}(n - p)\hat{\sigma}\sqrt{1 + \mathbf{x}_{t+\ell}^T(\mathbf{x}^T \mathbf{x})^{-1} \mathbf{x}_{t+\ell}}$$